NeoCASS Tutorial

Running NeoCASS from the command window without the GUI "some guide lines"



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Run the script **set_neocass_path.m** in the installation directory. That allows to include the NeoCASS routines into the current path.

Then change directory that you will use for your analysis. Paste in this path the aircraft model (*B747-400_reference.xml*) and the sizing maneuvers file (*pullup.inc*). The first file is created through Acbuilder, and the last one could be created either automatically, using the NeoCASS GUI, or manually, knowing the actual file's format.







Impose the desired number of iteration till convergence respecting a certain tolerance:

global NMAX EPS	(set as global)
NMAX = 3;	(number of iterations
EPS = 1e-3;	(tolerance)

<u>Hypothesis</u>: The *.xml* file contains all the a/c information (general geometry, stick model and technology). However, the 'guess' function deals the parts separately, so one should extract the stick model from the original file.

[~, stick_filename] = fileparts(xmlfilename);
stick = [stick_filename '.inc'];





Moreover, some other model clarifications must be set. Considering the reference B747 aircraft, fill the following fields:

model.Joined_wing = false; model.Strut_wing = false; model.EnvPoints = []; model.guessstd = true;

One last step, before starting the guess model generation, is initializing the process by creating a void structure:

init_guess_model;





Now it is time to process the raw aircraft using the *guess.m* function:

guess_model = guess(xmlfilename, xmlfilename, stick , trim_incfilename, model, false);

In this case:

guess_model = guess('B747-400_reference.xml', 'B747-400_reference.xml', stick, 'pullup.inc', model, false);





At the first phase one have to provide all the essential inputs for performing the trim analysis. Two inputs are, of course, the results of the previous step GUESS: the aircraft and the configuration file (both are '.inc').

Secondly, one have to provide a file containing the trim condition, that could differ from the dimensioning one (pullup.inc)

Another input file would be the one containing the **reference parameters** and the **solver ID**: **trim_param.inc**. It has the structure below:





One have to create and INCLUDE file named trim.dat that collect all the input required by the trim solver. The trim.dat file has the following structure:

INCLUDE C:\directory\Nameac.inc INCLUDE C:\directory\NameacCONM_CONF1.inc INCLUDE C:\directory\pullup.inc INCLUDE C:\directory\trim_param.inc

Now everything is ready to performing the trim analysis. Use these commands to load the model and start the solver:

global guess_model

guess_model = load_nastran_model('Nameac.inc');

solve_free_lin_trim();

At the end of the process the solver communicates where the results are saved:

Solution summary exported to *C*:*directory**trim_man_1.txt* file.





Initially one have to provide all the essential inputs for performing the MODAL analysis. Two inputs are, of course, the results of the previous step GUESS: the aircraft and the configuration file (both are '.inc').

Secondly, one have to provide a file containing the **reference parameters**, the **solver ID** and the modes driving information: **modal_param.inc**. It has the following structure:



frequency range [0,100] Hz; select the first 30 modes





One have to create and INCLUDE file named **modal.dat** that collect all the input required by the modal solver. The modal.dat file has the following structure:

INCLUDE C:\directory\Nameac.inc INCLUDE C:\directory\NameacCONM_CONF1.inc INCLUDE C:\directory\modal_param.inc

Now everything is ready to performing the modal analysis. Use these commands to load the model and start the solver:

global guess_model

guess_model = load_nastran_model('Nameac.inc');

solve_eig();

At the end of the process the results will be displayed in the command window





As usual, one have to create the INCLUDE file named **flutter.dat** that collect all the input required by the flutter solver. The flutter.dat file has the following structure:

INCLUDE C:\directory\Nameac.inc INCLUDE C:\directory\NameacCONM_CONF1.inc INCLUDE C:\directory\flutter_param.inc

... where the *flutter_param.inc* is shown in the following page. In this file one have to select the mode of interest for further analysis from the results' domain of the previous modal solver.

At this point one could use the *run.flutter* function, however using another, higher level, function is more straightforward: *init_dyn_model(flutter.dat)*

The parameters decribed in flutter_param.inc are sufficient for flutter analysis, even if the init_dyn_model function may require more input for a further dynamic response analysis with NeoRESP.



SMATCAD : FLUTTER problem



\$-----7----8----**\$ VLM parameters** \$------3-----4-----5-----6------7-----8-\$------3------4-----5------6------7-----8-4 36.2 126.8 0 0 0 AEROS SOL 145 \$------8-**S** Flutter solver parameters \$-----8-AERO 126.8 300 4 1.225 0 0 2 50 36.2 \$------8-**\$ Reduced frequency and Mach number list** \$-----7----8-**MKAERO1** 0.5 0.001 0.01 0.05 0.1 0.2 0.5 1.0 2.0 \$------8-**\$ Eigen-analysis cards** \$-----8-**EIGR** 1 0 1000 30 MASScont.....

.....cont.....

SMATCAD : FLUTTER problem



V-g plot resulting from flutter analysis. In this case, no flutter is detected.





In this section the main predefined plot available in NeoCASS are highlighted. In particular:

- Placard diagram
- Velocity margins vs altitude
- section-wise sizing shear force in fuselage, wing, vertical and horizontal tail
- section-wise sizing bending moment in fuselage, wing, vertical and horizontal tail
- section-wise moment of inertia of fuselage
- section-wise sizing torque of wing, vertical tail and horizontal tail
- Fuselage thickness
- span-wise skin thickness of wing, vertical tail and horizontal tail
- span-wise web thickness of wing, vertical tail and horizontal tail
- Out-of-plane moment of inertia (I1 [m4]) wing, vertical tail and horizontal tail
- In-plane moment of inertia (I2 [m4]) wing, vertical tail and horizontal tail
- torsional constant (J [m4]) wing, vertical tail and horizontal tail
- bearing structure mass distribution along fuselage, wing, vertical tail and horizontal tail
- etc







In order to plot velocity margins as function of altitude use:

plot_zM(nfig, VA, HA, VC, HC, VD, HD)

nfig : figure number VA, VC, VD : characteristic velocities [m/s] HA, HC, HD : altitude at which the previous velocities are defined [m]





Loading the guess module's results (*load guess_model*) one could plot many interesting variables trends along the main aircraft structures. Use:

plot_guess_model(set, fignr, guess_model)

fignr: figure number *guess_model*: name of the file where guess results are stored *set* = 1,2,3,4,6,7,8,11,12 or13 corresponds to predefined plot





The same will be for the next figures. Set=2: section-wise sizing bending (x1,5) in the fuselage





Set=3: section-wise moment of inertia of fuselage









Set=6: section-wise sizing shear force (x1,5) wing, vertical tail and horizontal tail





Set=7: section-wise sizing bending (x1,5) wing, vertical tail and horizontal tail





Set=8: section-wise sizing torque (x1,5) wing, vertical tail and horizontal tail















Set=11: Out-of-plane moment of inertia (I1 [m4]) wing, vertical tail and horizontal tail





Set 12: in-plane moment of inertia (I2 [m4]) wing, vertical tail and horizontal tail









Set 14: bearing structure mass distribution along the fuselage





Set 15: bearing structure mass distribution along wing, vertical tail and horizontal tail





Internal Forces

Use the following command after performing at least a trim analysis:

global beam_model
Al_plot(ifig, IND, NLEVEL)

where:

ifig is the index of figure

IND is the index of internal load that is needed
IND = 1 : local Tx; (axial)
IND = 2 : local Ty; (vertical shear)
IND = 3 : local Tz; (horiz shear)
IND = 4 : local Mx; (torsion)
IND = 5 : local My; (out of plane bending)
IND = 6 : local Mz; (int of plane bending)

NLEVEL number of levels in contour

























