

# NeoCASS Tutorial

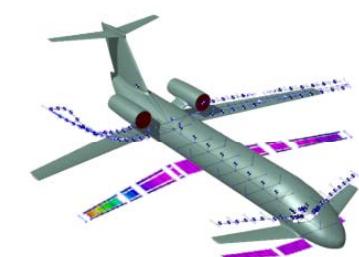
How to run a static aeroelastic analysis  
“three maneuver sizing”

Version 2.2(.790)

August 2017

## Outline

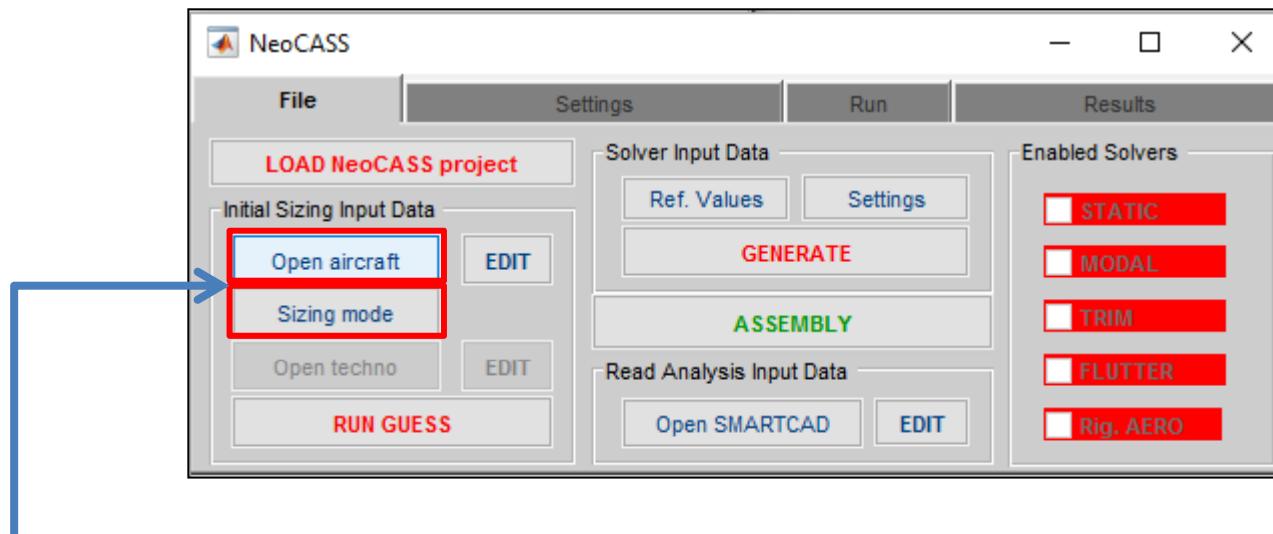
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| 2. Dimensioning Maneuvers                  | pag. | <a href="#">13</a> |
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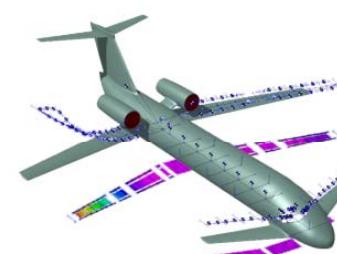


# Maneuvers Set Definition

Do not forget to run the script `set_neocass_path` in the installation directory. That allows to include the NeoCASS routines into the current path. Then change directory that you will use for your analysis and start *NeoCASS*, typing it in the command window.

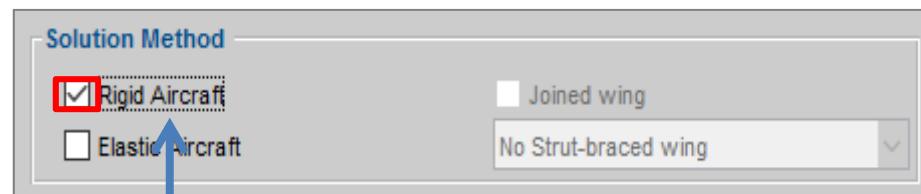
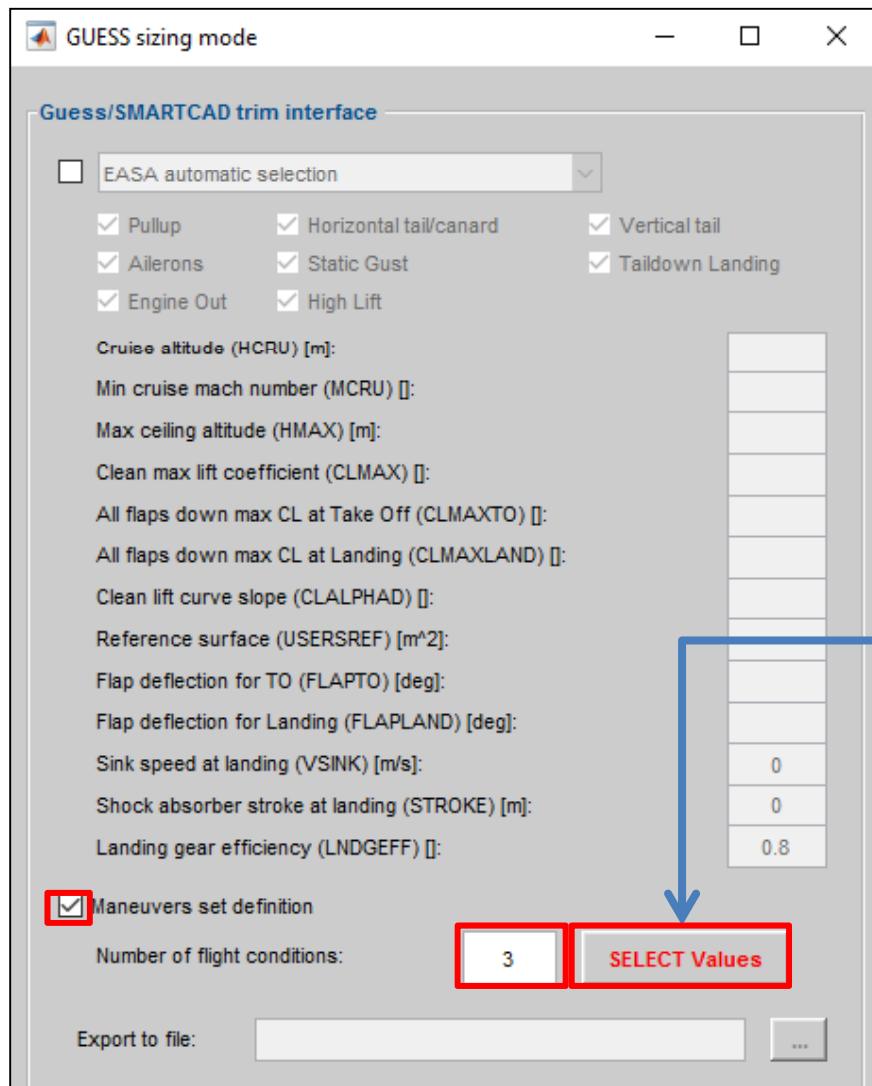


Open the aircraft model ('Open aircraft') and click on 'Sizing mode'. In this tutorial the `B747-400_reference.xml` is used.



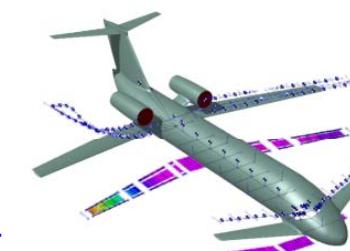


# Maneuvers Set Definition



In Solution Method select  
*'Rigid Aircraft'*.

To impose three user-defined  
load conditions click on:  
*'SELECT Values'*



# Maneuvers Set Definition: man. ID 1



Maneuver Definition

1      Mach: 0.5      Altitude [m]: 5000

Symmetric Maneuvers: Cruise/Climb (AoA, pitch control surfaces)

Anti-Symmetric Maneuvers: Sideslip levelled flight

Parameters:

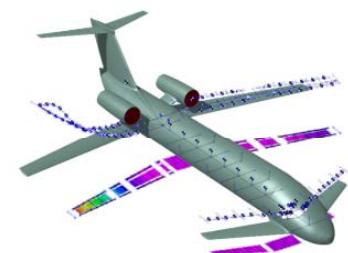
|  |   |                                     |      |
|--|---|-------------------------------------|------|
| Angle of attack (ANGLEA) [deg]:                        | 0 | Sideslip angle (SIDES) [deg]:       | 0    |
| Roll rate (ROLL) [1/s]:                                | 0 | p rate (URDD4) [1/s^2]:             | 0    |
| Pitch rate (PITCH) [1/s]:                              | 0 | q rate (URDD5) [1/s^2]:             | 0    |
| Yaw rate (YAW) [1/s]:                                  | 0 | r rate (URDD6) [1/s^2]:             | 0    |
| Elevator rotation (elev1r) [deg]:                      | 0 | X acc (URDD1) [m/s^2]:              | 0    |
| Canard rotation (elevC1r) [deg]:                       | 0 | Y acc (URDD2) [m/s^2]:              | 0    |
| Aileron rotation (aileronr) [deg]:                     | 0 | Z acc (URDD3) [m/s^2]:              | 34.3 |
| Rudder rotation (rudder1) [deg]:                       | 0 | Vertical speed (VGUST) [EAS m/s]:   | 0    |
| 1st Flap rotation (flap1r) [deg]:                      | 0 | Strut efficiency (LNDGEFF) []:      | 0    |
| 2nd Flap rotation (flap2r) [deg]:                      | 0 | Sink speed (VSINK) [m/s]:           | 0    |
| <input checked="" type="checkbox"/> Symmetric maneuver |   | Shock absorber stroke (STROKE) [m]: | 0    |

User defined maneuver      Save      Discard

For example, define three maneuvers: two symmetric and one anti-symmetric.

*Pull Up maneuver:*  
Z acceleration =  
 $3.5 \times g$ .

Clicking 'Save' the next maneuver's setting window will appear.



# Maneuvers Set Definition: man. ID 2



Maneuver Definition

2      Mach: 0.5      Altitude [m]: 5000

Symmetric Maneuvers: Cruise/Climb (AoA, pitch control surfaces)

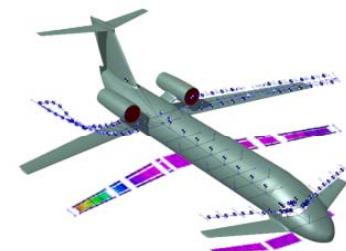
Anti-Symmetric Maneuvers: Sideslip levelled flight

Parameters:

|  |   |                                     |       |
|--|---|-------------------------------------|-------|
| Angle of attack (ANGLEA) [deg]:                        | 0 | Sideslip angle (SIDES) [deg]:       | 0     |
| Roll rate (ROLL) [1/s]:                                | 0 | p rate (URDD4) [1/s^2]:             | 0     |
| Pitch rate (PITCH) [1/s]:                              | 0 | q rate (URDD5) [1/s^2]:             | 0     |
| Yaw rate (YAW) [1/s]:                                  | 0 | r rate (URDD6) [1/s^2]:             | 0     |
| Elevator rotation (elev1r) [deg]:                      | 0 | X acc (URDD1) [m/s^2]:              | 0     |
| Canard rotation (elevC1r) [deg]:                       | 0 | Y acc (URDD2) [m/s^2]:              | 0     |
| Aileron rotation (aileronr) [deg]:                     | 0 | Z acc (URDD3) [m/s^2]:              | -14.7 |
| Rudder rotation (rudder1) [deg]:                       | 0 | Vertical speed (VGUST) [EAS m/s]:   | 0     |
| 1st Flap rotation (flap1r) [deg]:                      | 0 | Strut efficiency (LNDGEFF) []:      | 0     |
| 2nd Flap rotation (flap2r) [deg]:                      | 0 | Sink speed (VSINK) [m/s]:           | 0     |
| <input checked="" type="checkbox"/> Symmetric maneuver |   | Shock absorber stroke (STROKE) [m]: | 0     |

User defined maneuver      Save      Discard

Negative g maneuver:  
Z acceleration =  
 $-1.5 \cdot g$ .



# Maneuvers Set Definition: man. ID 3



Maneuver Definition

3      Mach: 0.5      Altitude [m]: 5000

Symmetric Maneuvers: Cruise/Climb (AoA, pitch control surfaces)

Anti-Symmetric Maneuvers: Sideslip levelled flight

Parameters:

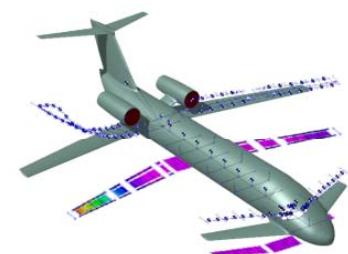
|                                       |                                     |
|---------------------------------------|-------------------------------------|
| Angle of attack (ANGLEA) [deg]:       | Sideslip angle (SIDES) [deg]: 20    |
| Roll rate (ROLL) [1/s]:               | p rate (URDD4) [1/s^2]: 0           |
| Pitch rate (PITCH) [1/s]:             | q rate (URDD5) [1/s^2]: 0           |
| Yaw rate (YAW) [1/s]:                 | r rate (URDD6) [1/s^2]: 0           |
| Elevator rotation (elev1r) [deg]:     | X acc (URDD1) [m/s^2]:              |
| Canard rotation (elevC1r) [deg]:      | Y acc (URDD2) [m/s^2]:              |
| Aileron rotation (aileronr) [deg]:    | Z acc (URDD3) [m/s^2]: 9.81         |
| Rudder rotation (rudder1) [deg]:      | Vertical speed (VGUST) [EAS m/s]: 0 |
| 1st Flap rotation (flap1r) [deg]:     | Strut efficiency (LNDGEFF) []: 0    |
| 2nd Flap rotation (flap2r) [deg]:     | Sink speed (VSINK) [m/s]: 0         |
| Shock absorber stroke (STROKE) [m]: 0 |                                     |

Symmetric maneuver

User defined maneuver

Save   Discard

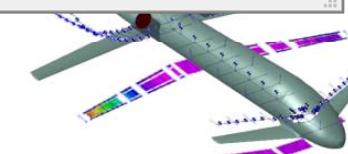
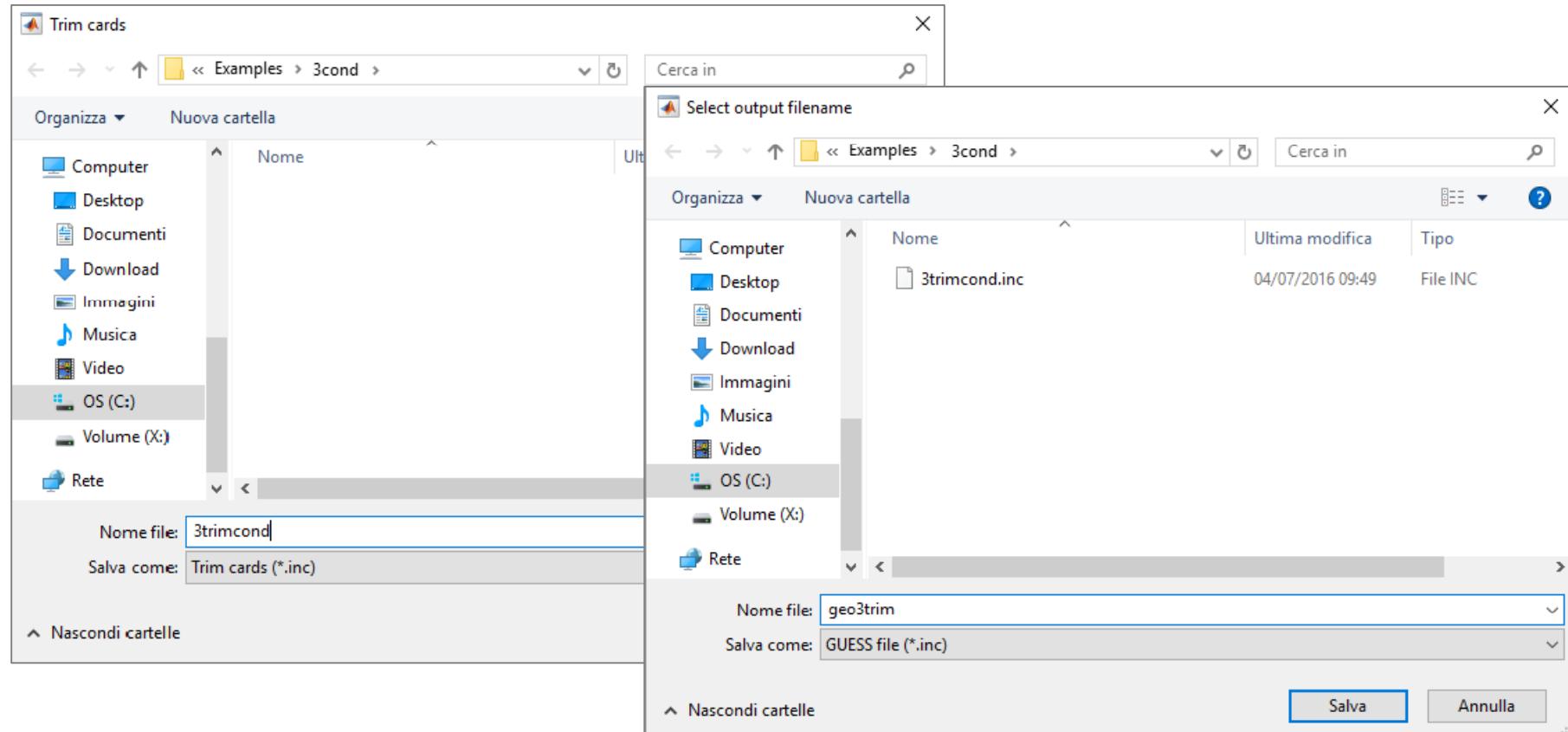
*Sideslip maneuver:  
sideslip angle = 20°*



# Running GUESS



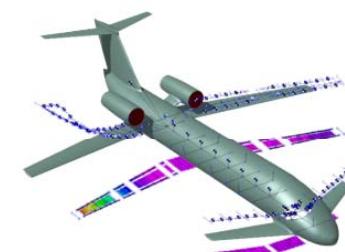
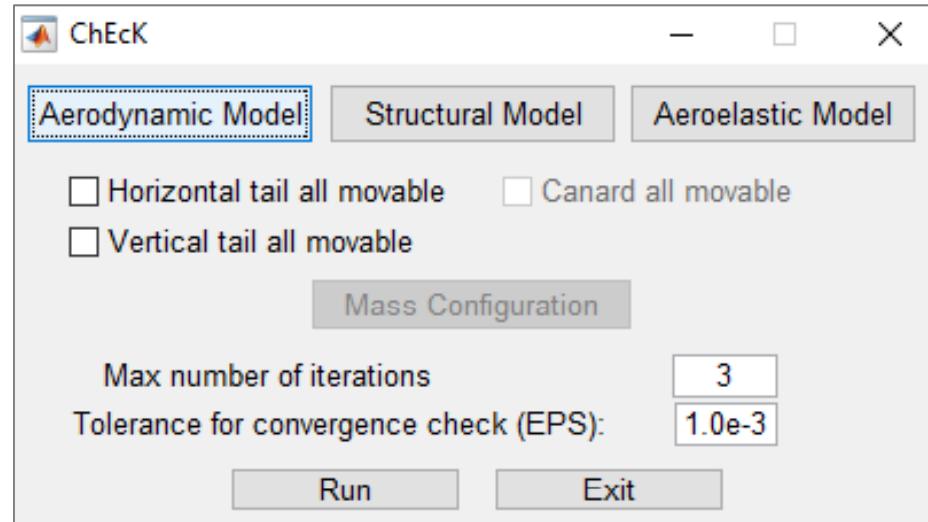
Save the trim condition in a .inc file (*3trimcond.inc*) and run guess creating *geo3trim.inc*



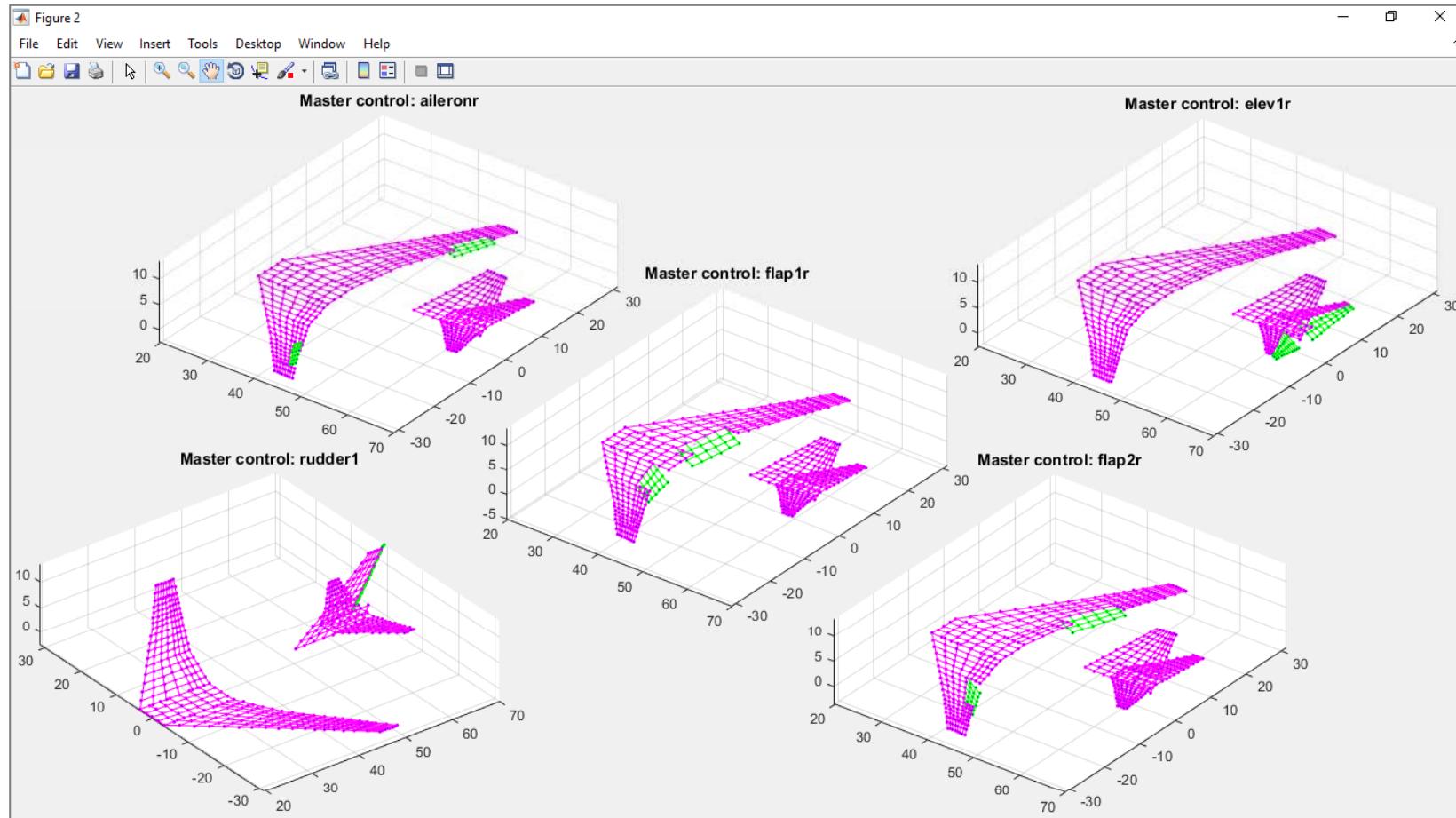
# ChEcK phase



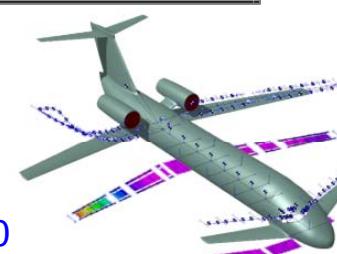
The *ChEcK* window comes up in order to check the way your aircraft is modeled. In the three slide below there is an output example of *Aerodynamic, Structural and Aeroelastic Models* of *B747-400*.



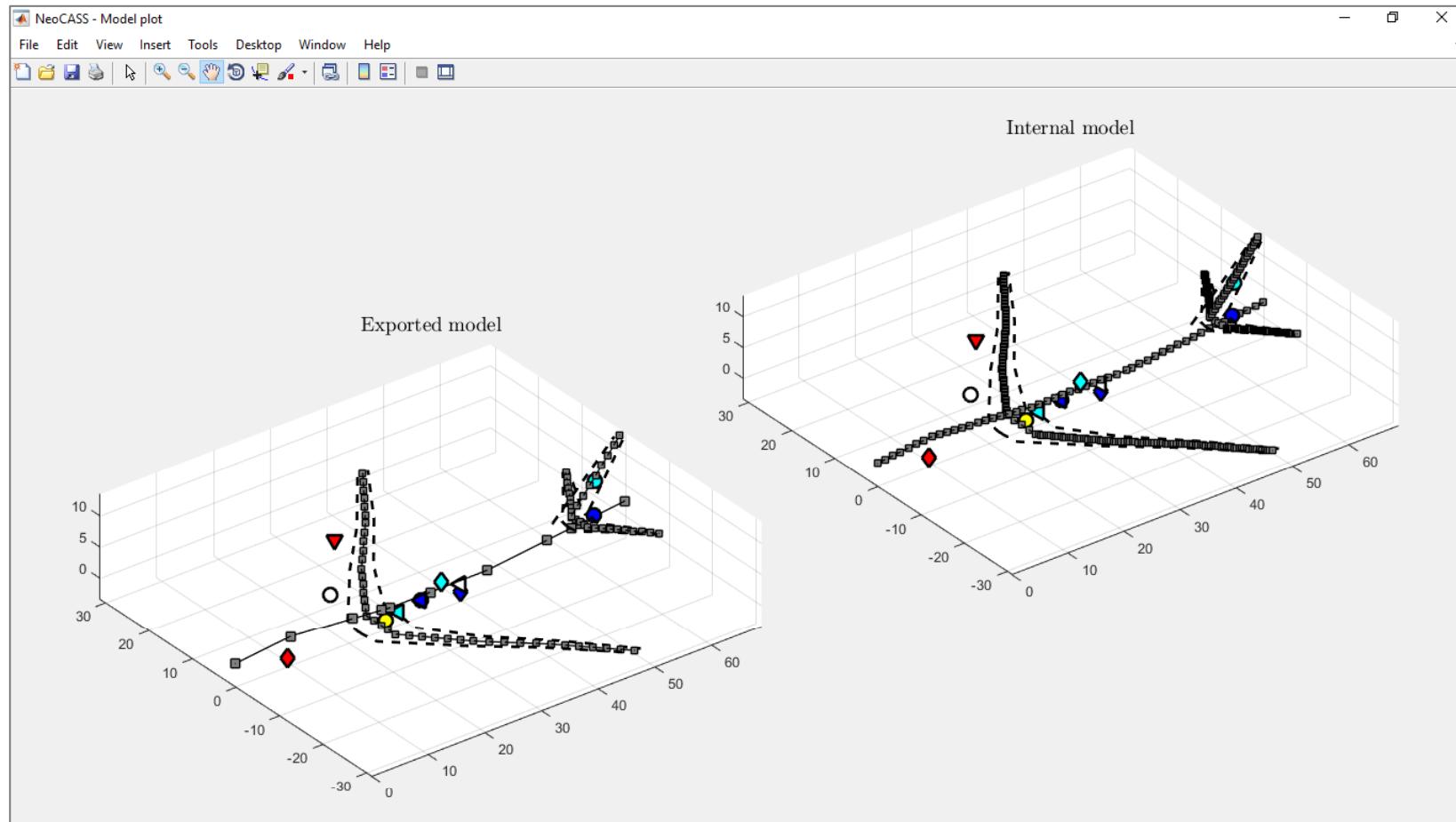
# ChEcK phase



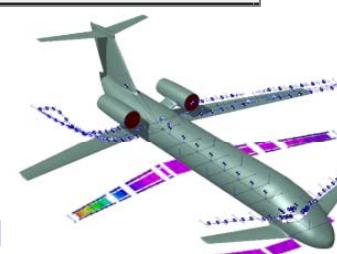
Aerodynamic Model



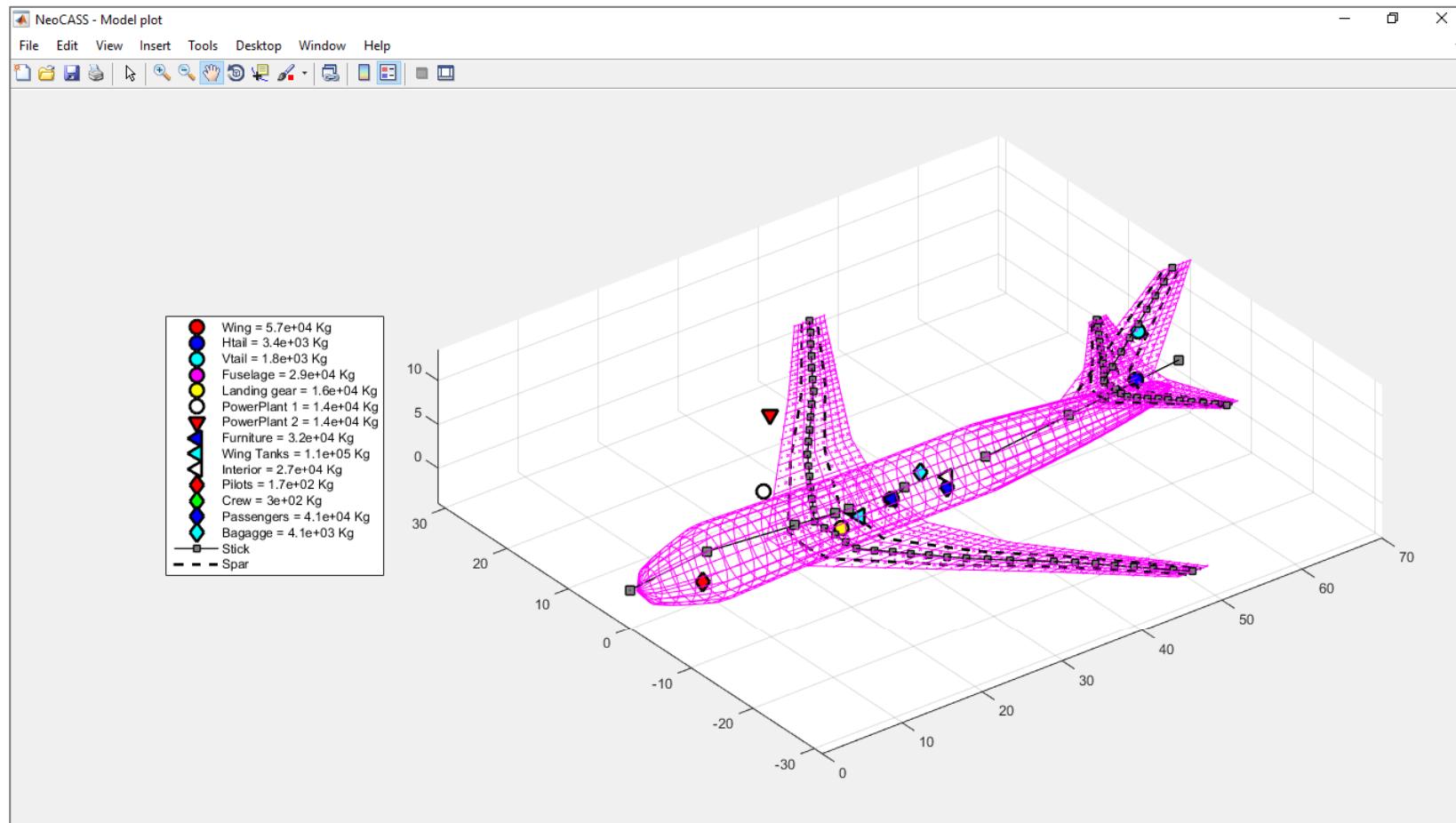
# ChEcK phase



Structural Model

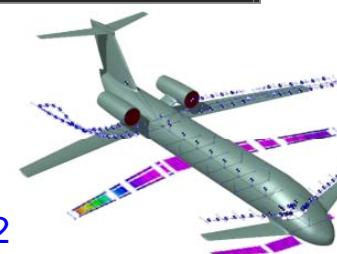


# ChEcK phase



Aeroelastic Model

Static aeroelastic analysis – V2.2.790 - Rel.1 August 2017 - pag. 12





# Dimensioning Maneuvers

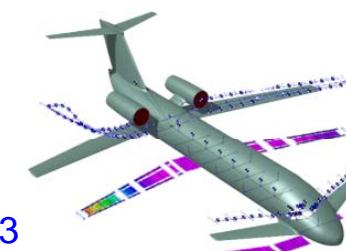
If everything goes well, the output will be similar to this one:

```
----- CONVERGENCE -----
- Refinement loop history:
  Iter 1: Total structural mass: 155434 Kg. Tolerance: 1.284e-03.
  Iter 2: Total structural mass: 152528 Kg. Tolerance: 1.867e-02.

- GUESS model saved in C:\NeoCASS_PG\Examples\PROVA\static_3cond\geo3trim_guess.mat file.
- GUESS summary saved in C:\NeoCASS_PG\Examples\PROVA\static_3cond\geo3trim_guess.txt file.
- SMARTCAD main file with OEW configuration saved in C:\NeoCASS_PG\Examples\PROVA\static_3cond\geo3trim.inc.
- SMARTCAD configuration file saved in C:\NeoCASS_PG\Examples\PROVA\static_3cond\geo3trimCONM_CONF1.inc file.
```

In order to view which maneuver was the most accountable for each a/c part (in terms of bending, shear and torque), one have to load the guess result and process these data through the '*plot\_sizing\_man*' function.

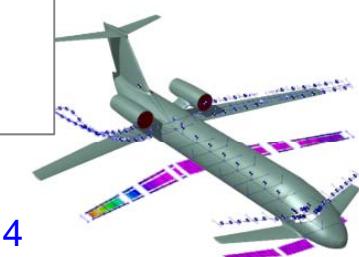
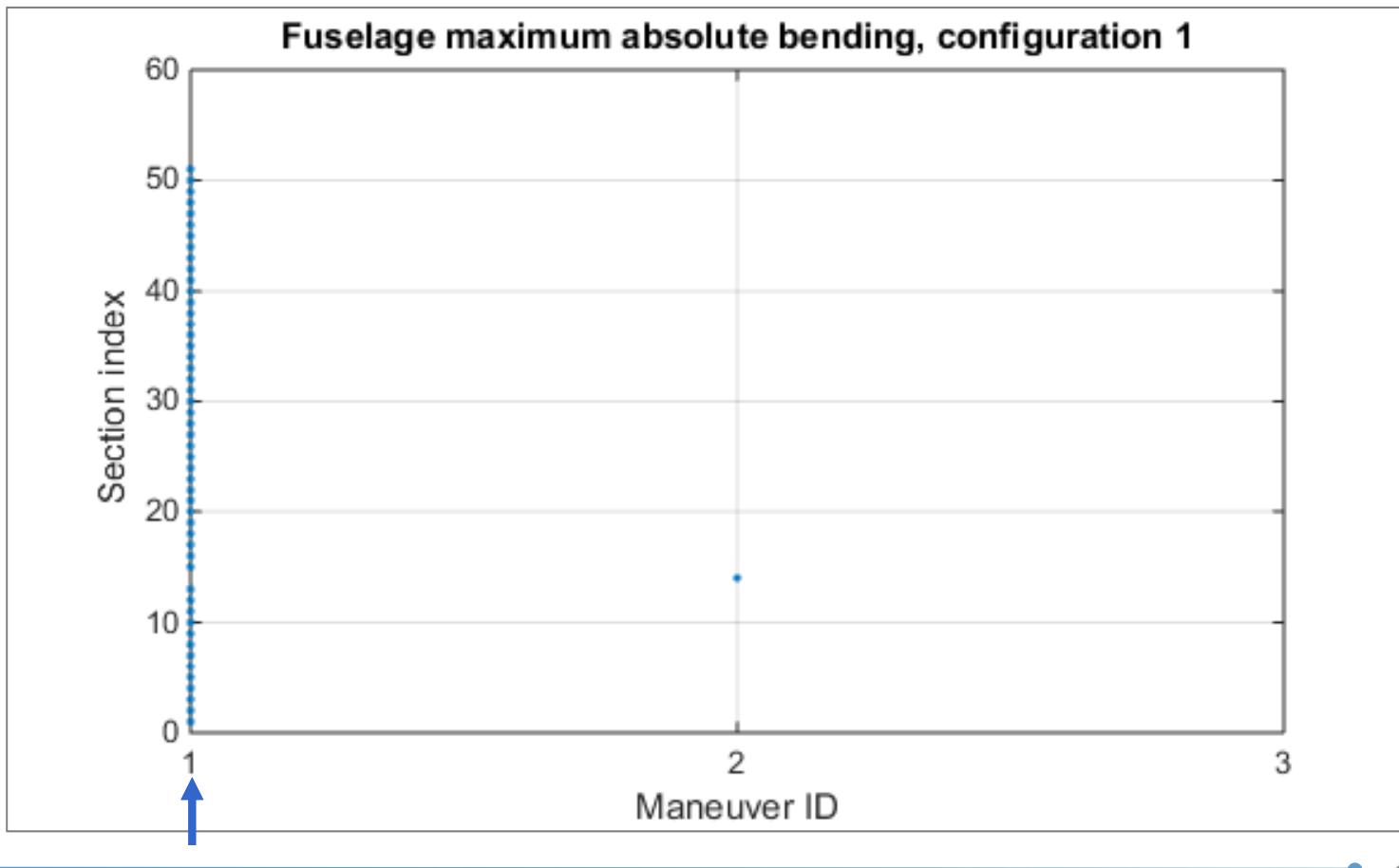
```
>> load('geo3trim_guess.mat')
>> plot_sizing_man(guess_model.loads, guess_model, 1, [0.1:0.1:0.9], 1)
```





# Dimensioning Maneuvers

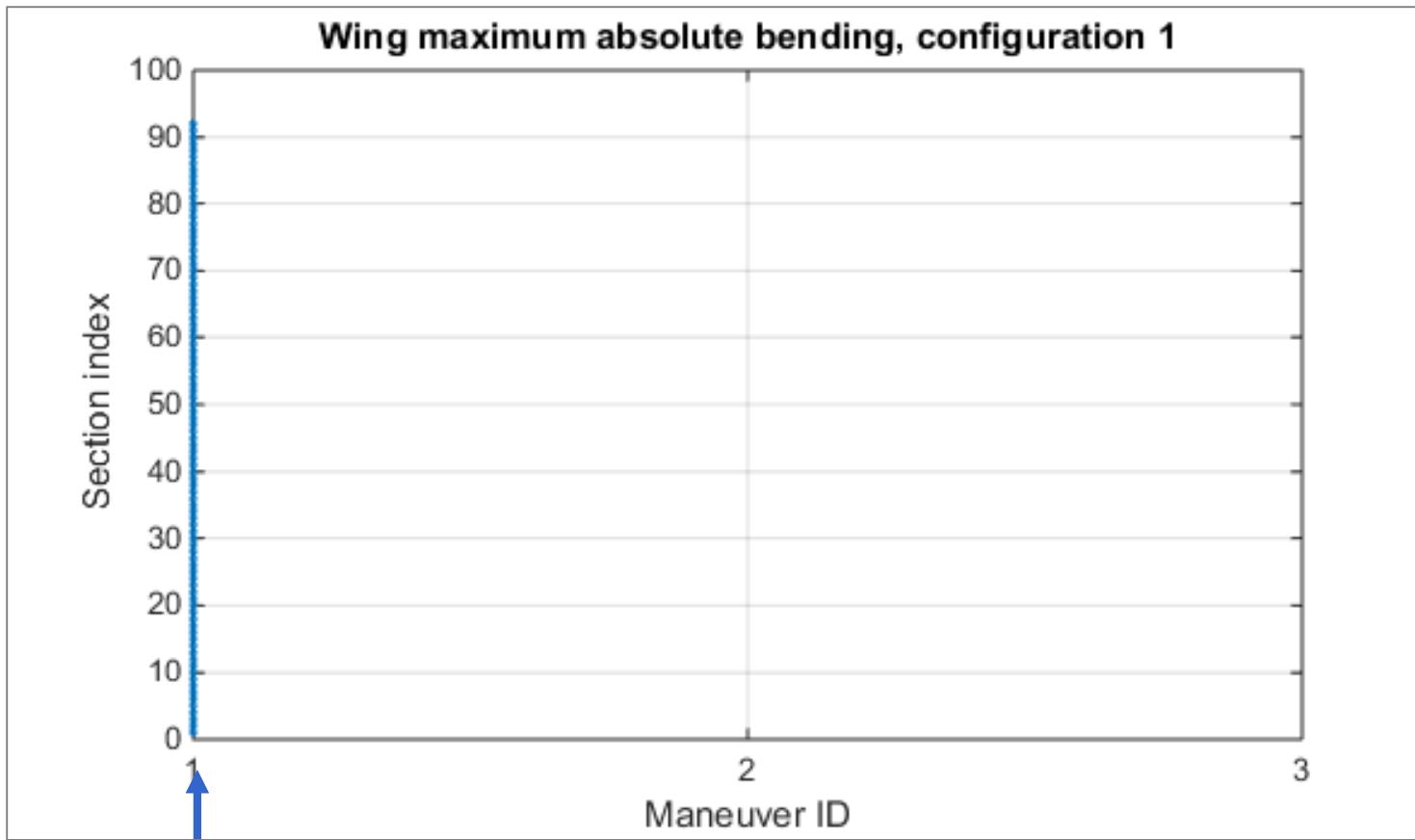
For instance, the sizing maneuver of the fuselage in bending loading is predictably the pull-up m. (ID 1)



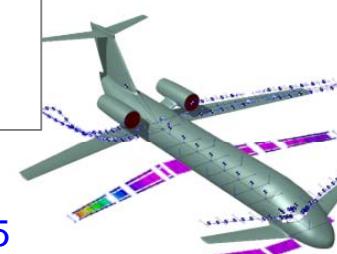


# Dimensioning Maneuvers

The same will be for bend, torque and shear of wings.



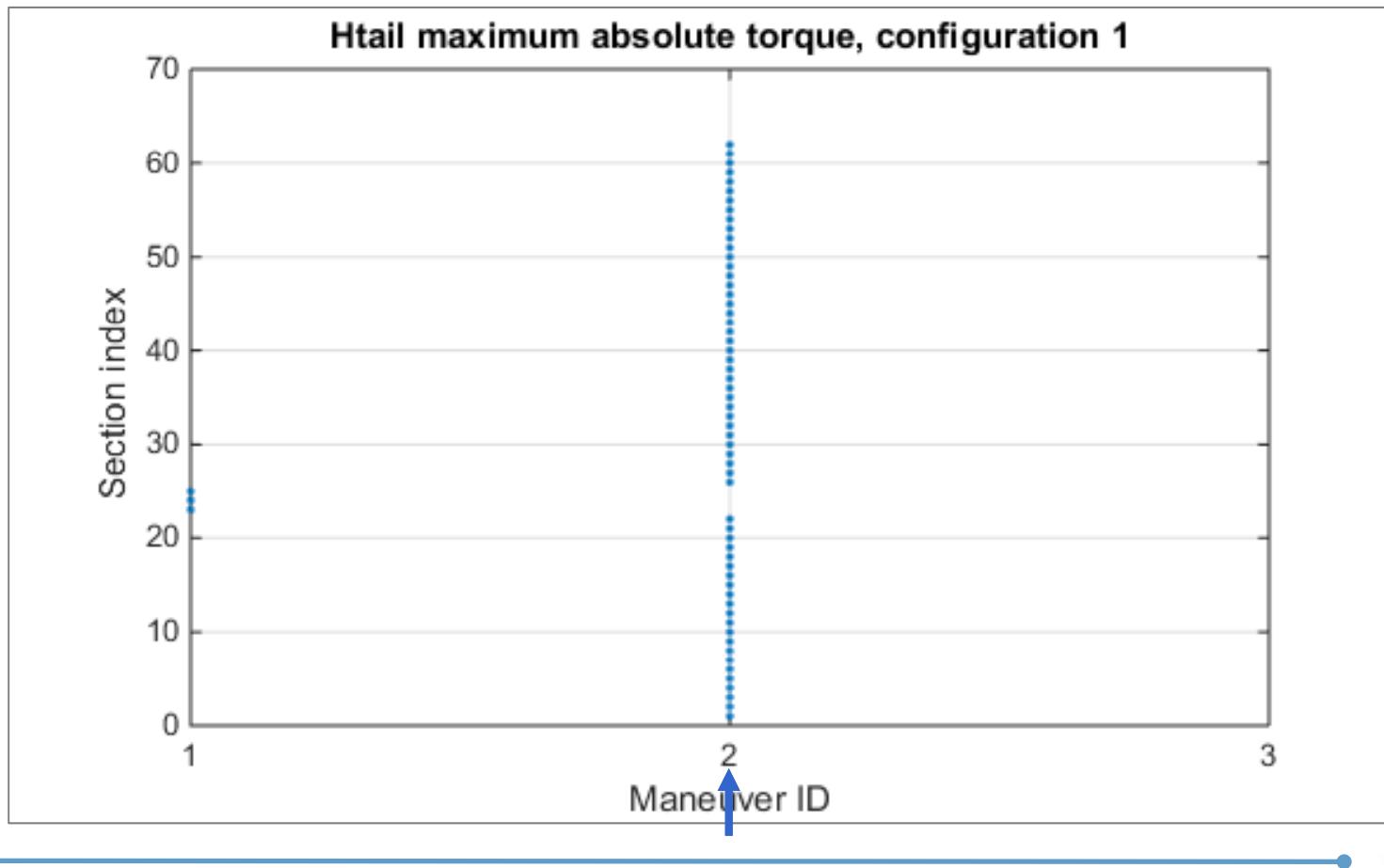
$p = 2 :$   
wings



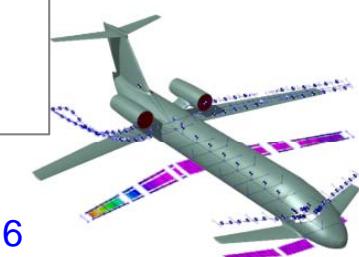


# Dimensioning Maneuvers

The negative g maneuver (ID 2) is the dimensioning one for horizontal tail as far as the torque loading is considered.



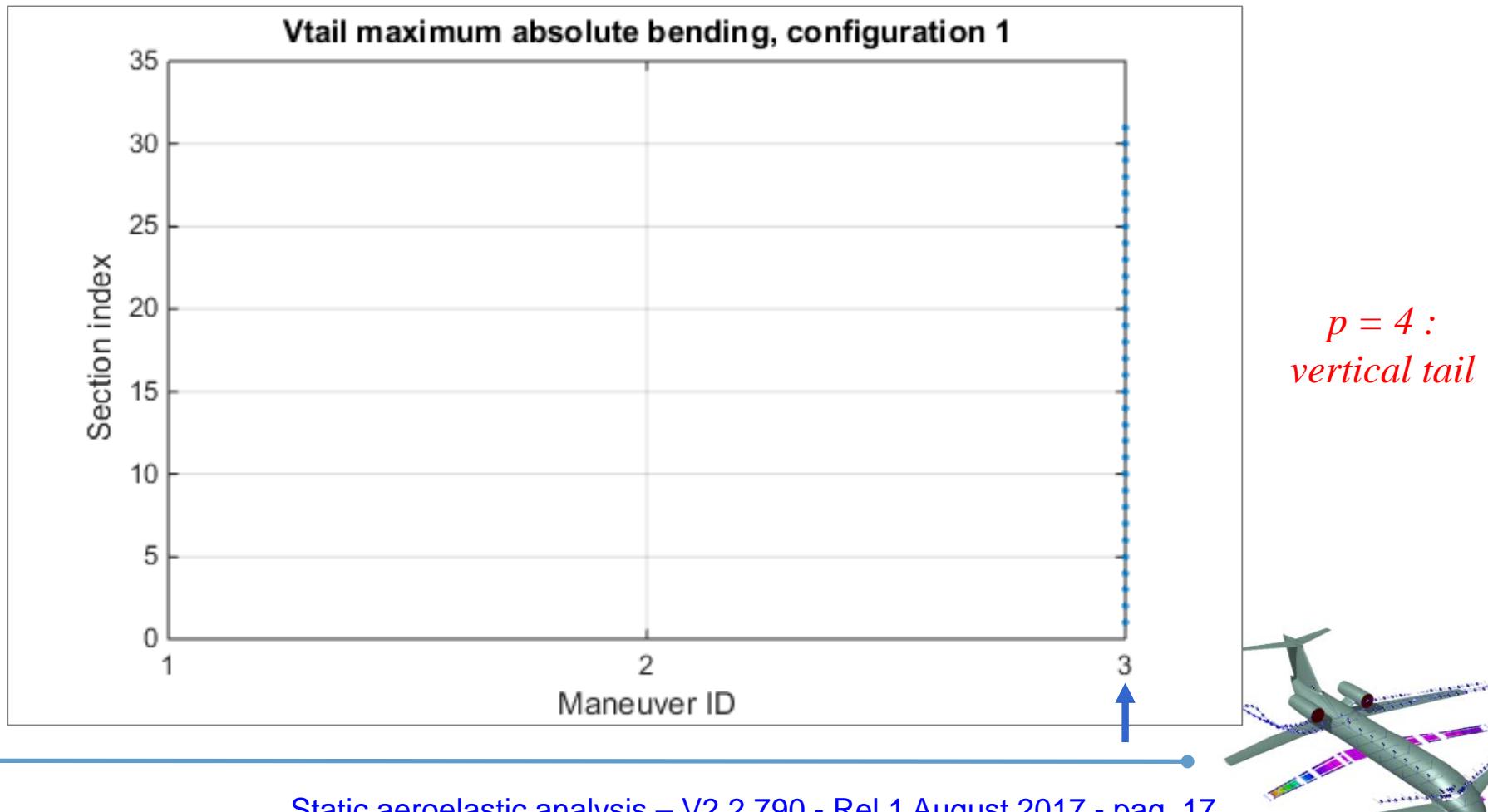
$p = 3 :$   
*horizontal  
tail*





# Dimensioning Maneuvers

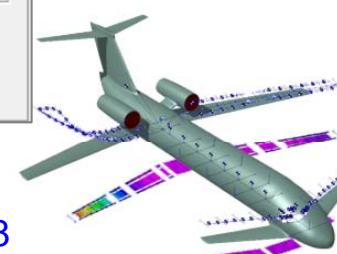
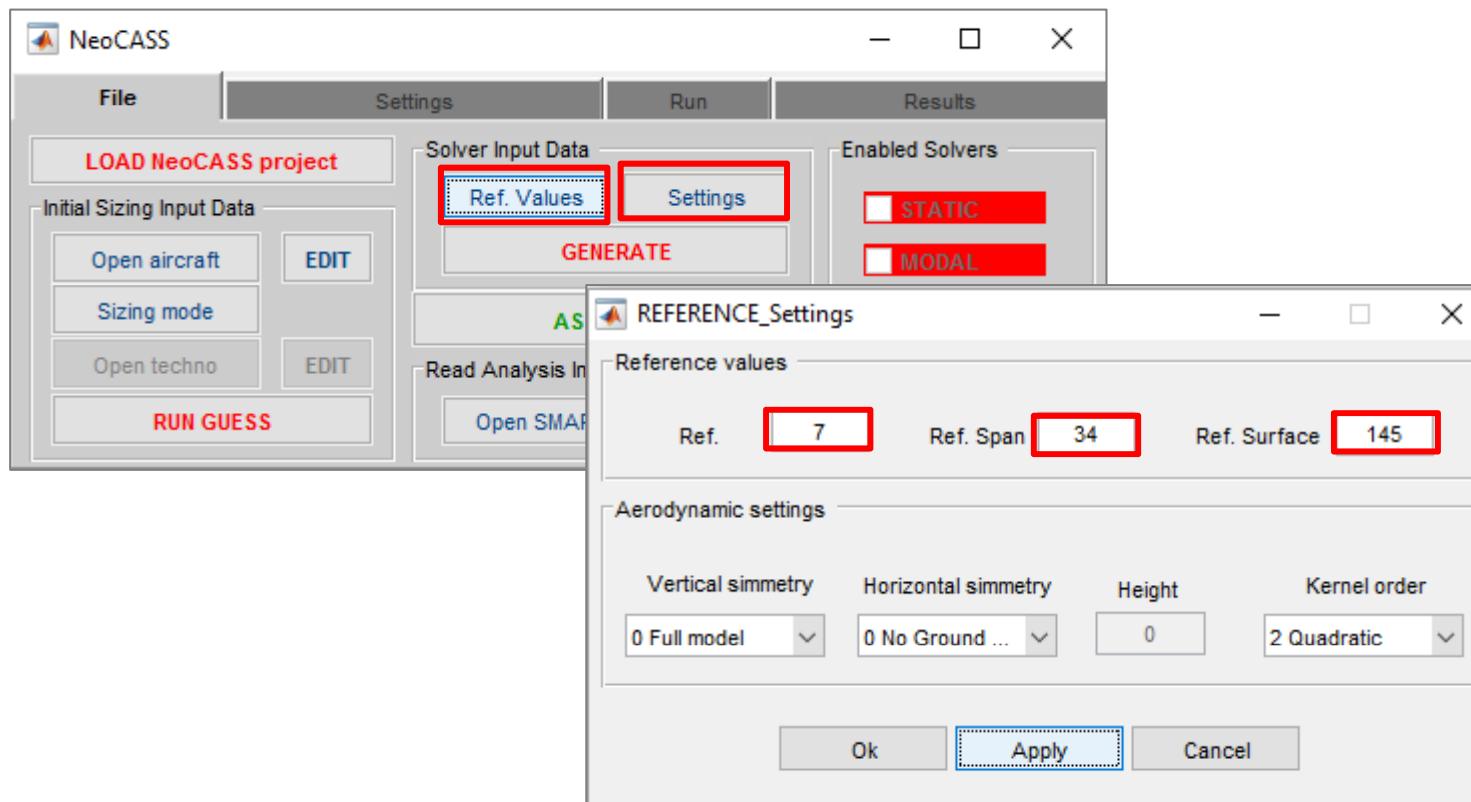
Finally, the side slip m. (ID 3) is the most significant for the vertical tail sizing.



# Running a ‘TRIM’ analysis

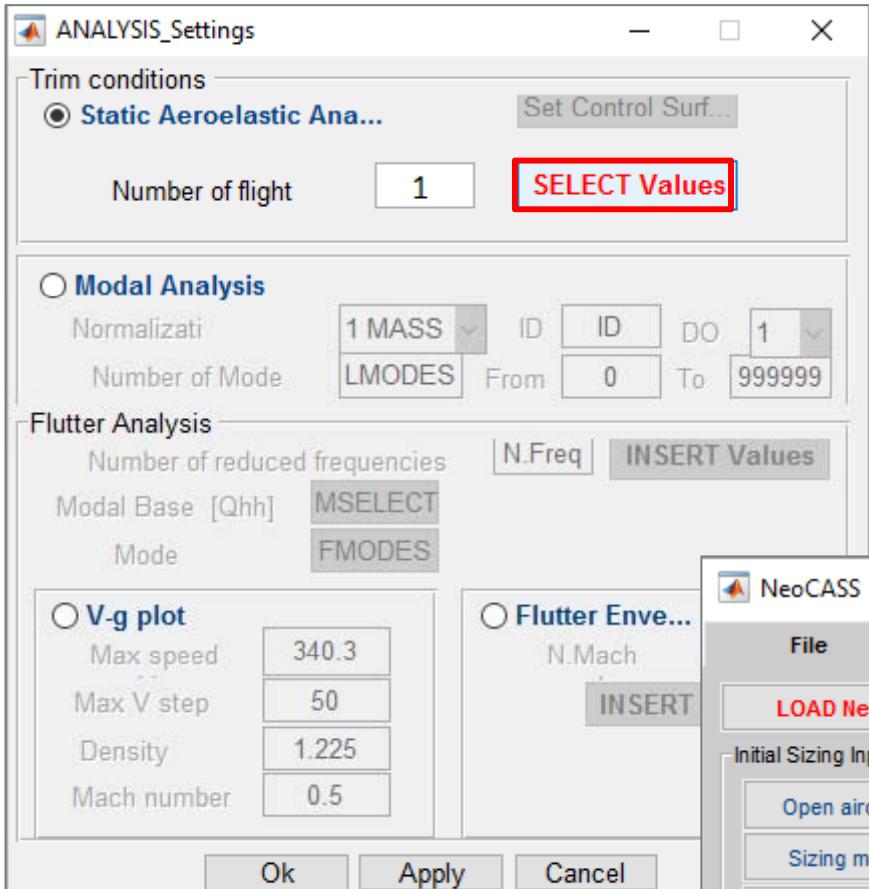


Set *Reference Values* and then press *Settings* for assigning loading details for further analysis.



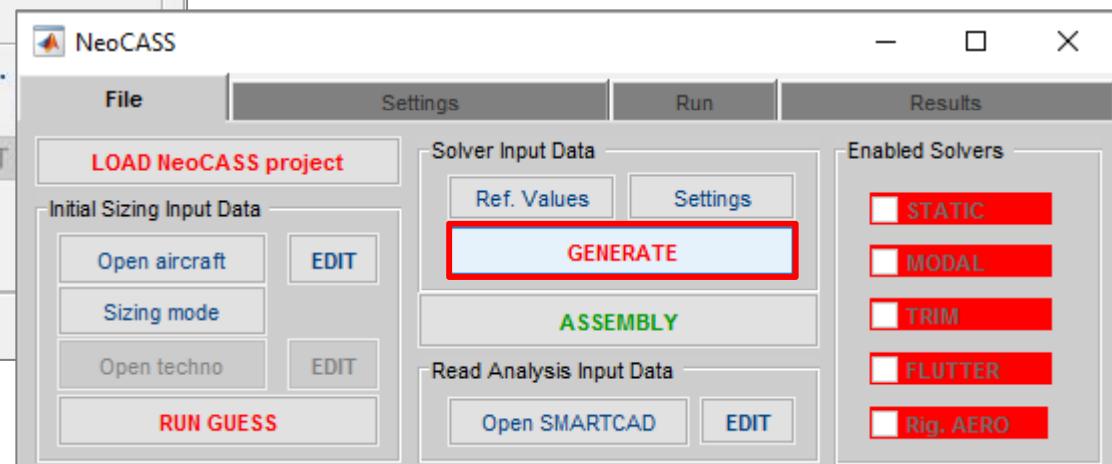


# Running a 'TRIM' analysis

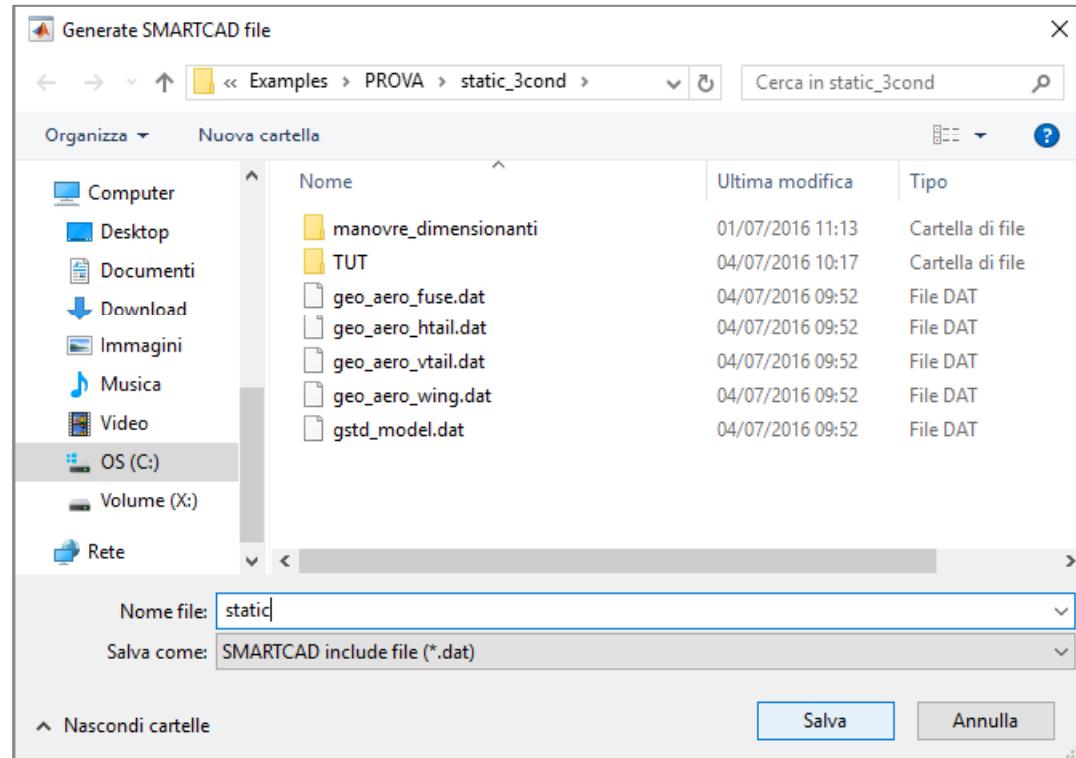


Select '*Static Aeroelastic Analysis*' and *SELECT* the *Values* for one out the three flight condition analyzed before during GUESS module, for instance 'pull-up'.

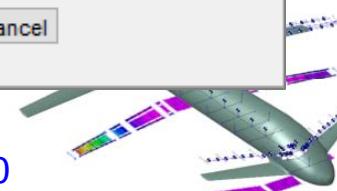
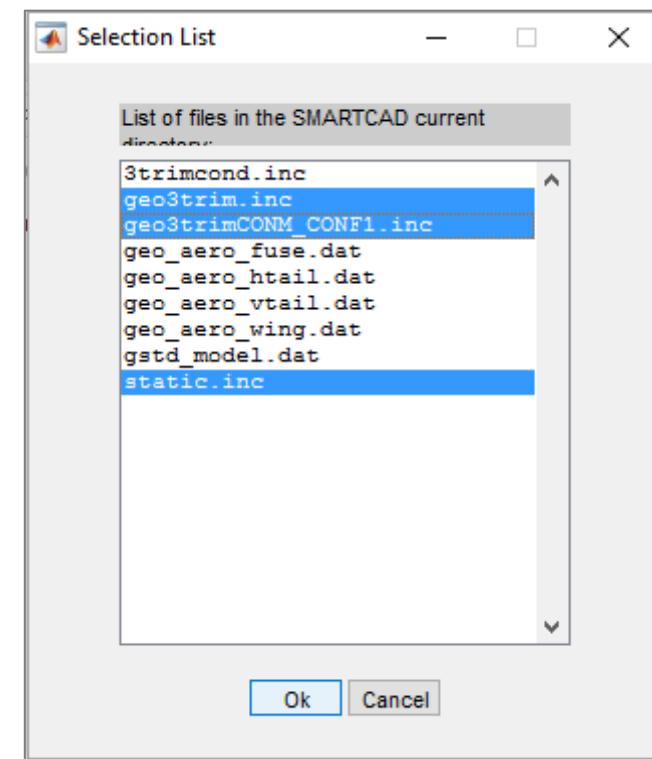
Then *GENERATE* the *static.inc* file that contains these information.



# Running a 'TRIM' analysis



Finally, as usual, collect the geometric and analysis settings in one *static.dat* file.

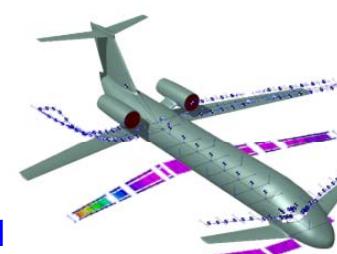
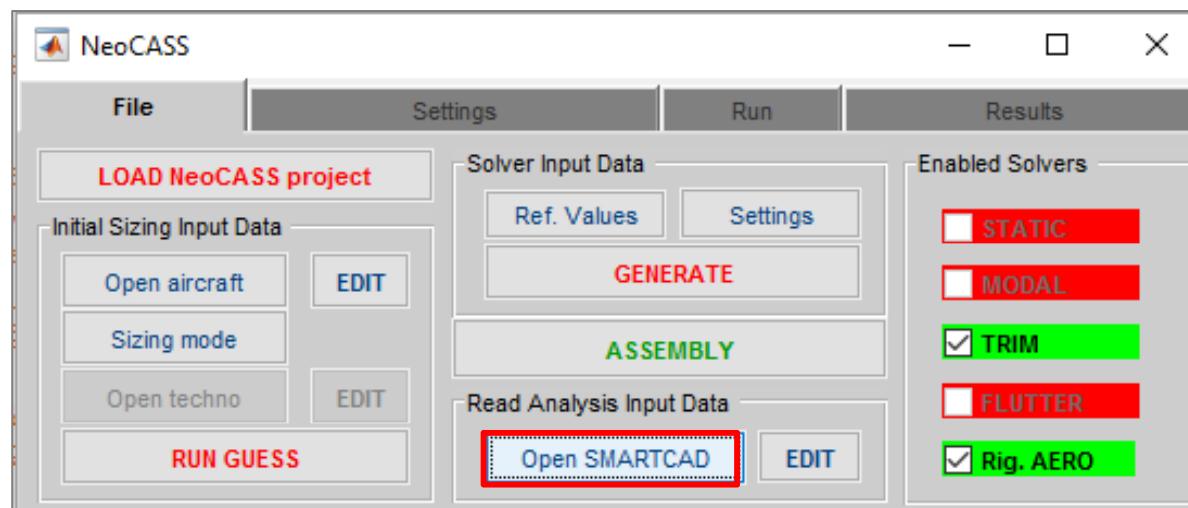




# Running a 'TRIM' analysis

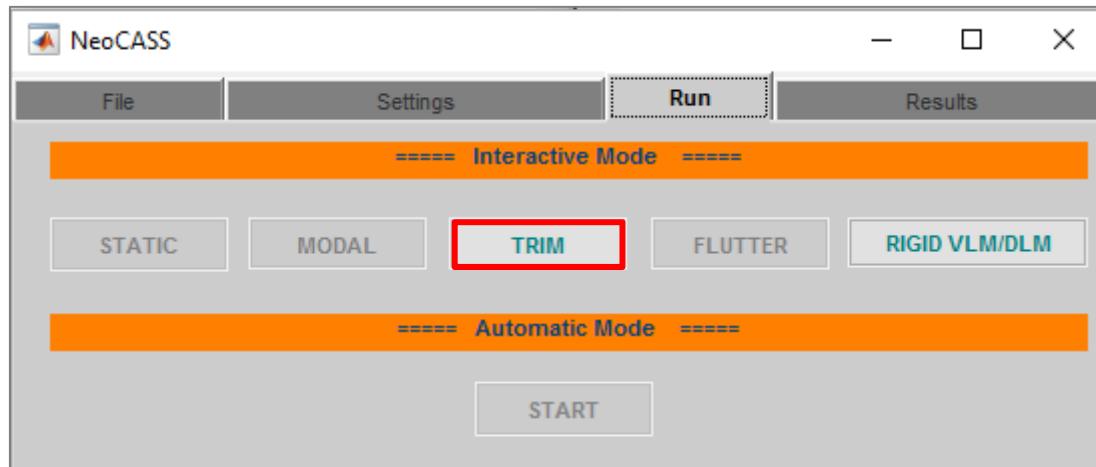
- Solver input data file: C:\NeoCASS\_PG\Examples\PROVA\static\_3cond\static.inc.
- Exporting parameters for steady VLM solver...done.
- SMARTCAD file: C:\NeoCASS\_PG\Examples\PROVA\static\_3cond\static.dat.

Loading the SMARTCAD file *static.dat* enables the TRIM and Rigid AERO analysis.

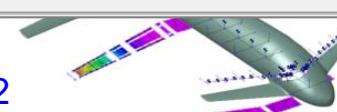
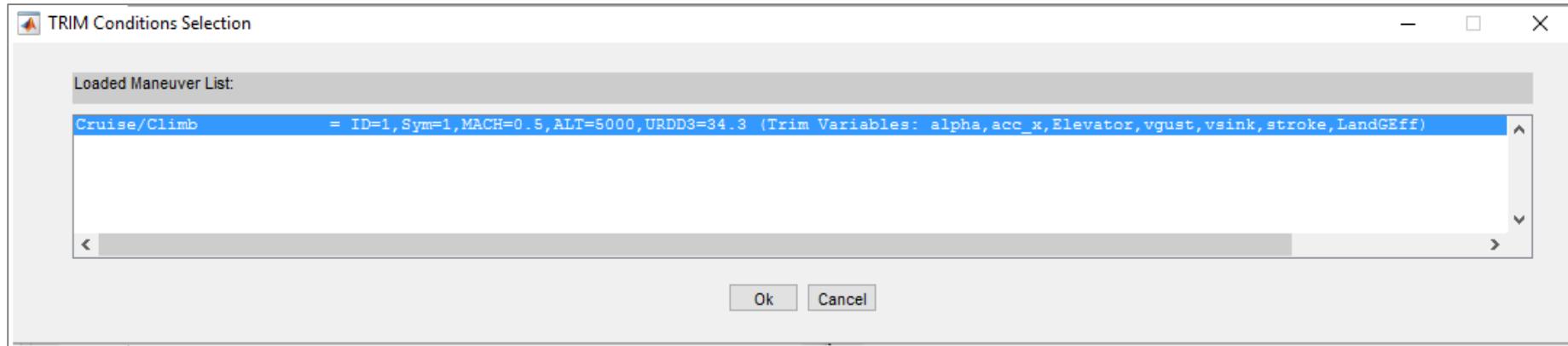




# Running a 'TRIM' analysis



Start running the TRIM process that equilibrate the ac in the selected flight condition.





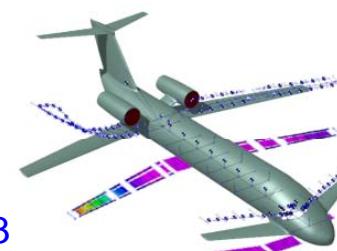
# Running a 'TRIM' analysis

In the command window the solver tells you about the actual process.

```
Solving linear static unrestrained trim (ID 1)...

- Setting internal database...done.
- Building aero-structural interpolation matrices...
  - Method: 1.
  - Assembling collocation points interpolation matrix...done.
  - Assembling nodes interpolation matrix...done.
  - Assembling vorticies interpolation matrix...done.
  - Assembling vorticies midpoint interpolation matrix...done.
  - Assembling body collocation points interpolation matrix...done.
done.

- Assembling stiffness matrix...done.
- Assembling mass matrix...done.
etc...
```





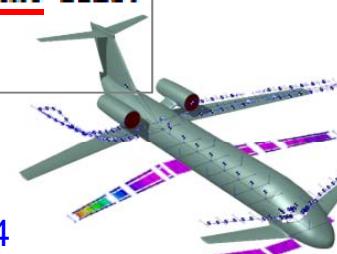
# Running a 'TRIM' analysis

The trim condition is solved.

```
Solving deformable aircraft trim condition...
- X acc:      -6.88209e-12 [m/s^2].
- Y acc:      0 [m/s^2].
- Z acc:      34.3 [m/s^2].
- P-DOT:      0 [rad/s^2].
- Q-DOT:      0 [rad/s^2].
- R-DOT:      0 [rad/s^2].

- Alpha:       38.1965 [deg].
- Sideslip:    0 [deg].
- Roll rate:   0 [-] (p*BREF/(2VREF)).
- Pitch rate:  0 [-] (q*CREF/(2VREF)).
- Yaw rate:    0 [-] (r*DREF/(2VREF)).
- Control flap1r: 0 [deg].
- Control flap2r: 0 [deg].
- Control aileronr: 0 [deg].
- Control elev1r: -6.25167 [deg].
- Control rudder1: 0 [deg].
done.
- Updating vlm model in Aero.lattice_defo...done.
- Solution summary exported to C:\NeoCASS_PG\Examples\PROVA\static_3cond\static man 1.txt file.
```

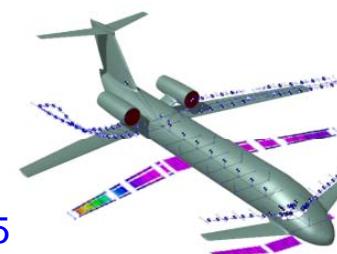
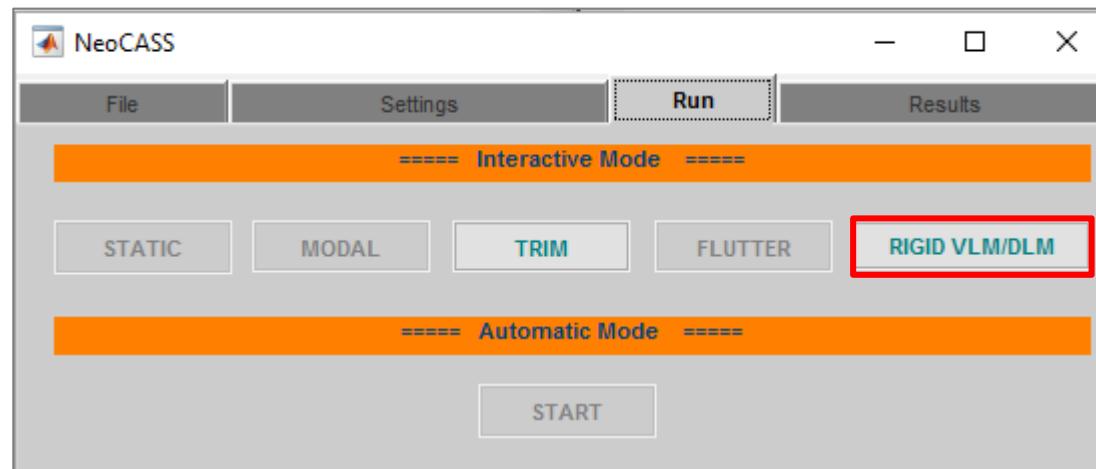
completed.



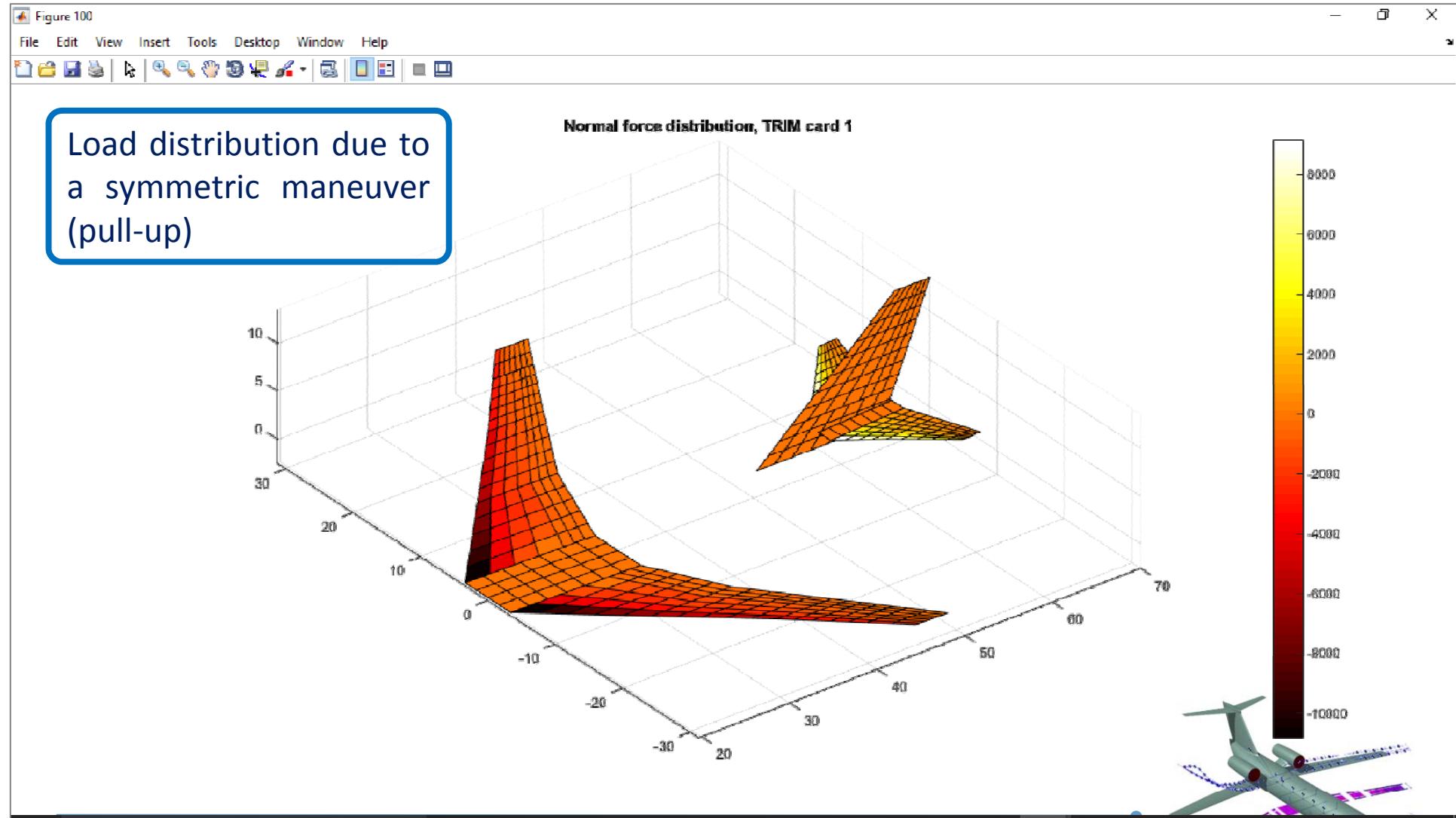
# Running a ‘Rigid VLM/DLM’ analysis



Now one could also run the ‘Rigid VLM/DLM analysis’. By clicking it the analysis will start automatically.



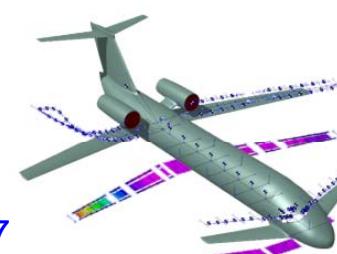
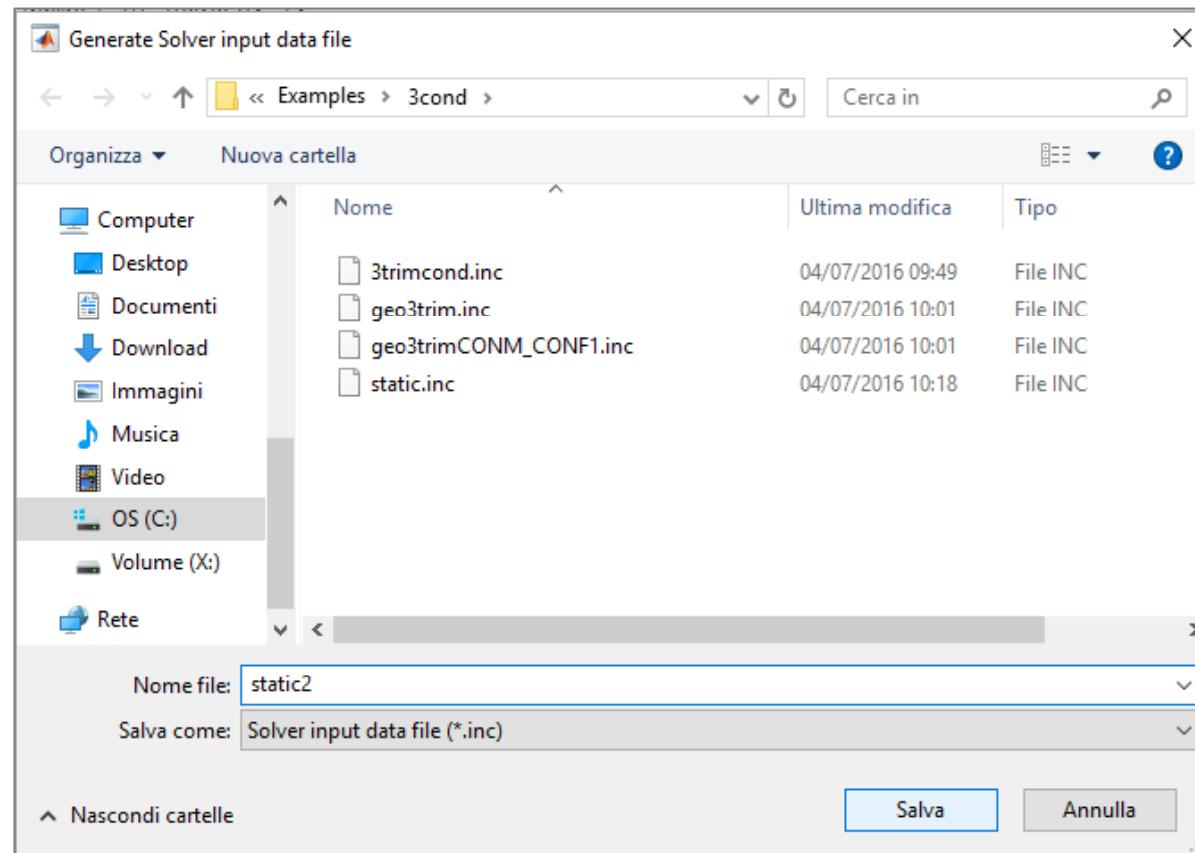
# Running a ‘Rigid VLM/DLM’ analysis



# Running another ‘TRIM’ and ‘Rigid VLM/DLM’ analysis



In order to analyze another loading condition, return to the [18th slide](#) and repeat the procedure for ‘sideslip’.



# Running another ‘TRIM’ and ‘Rigid VLM/DLM’ analysis

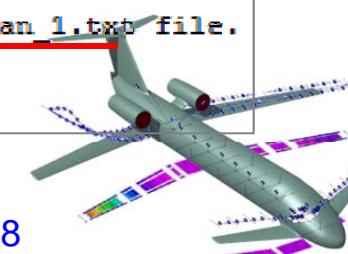


The new trim condition is solved:

```
Solving deformable aircraft trim condition...
- X acc:      -3.36379e-12 [m/s^2].
- Y acc:      1.04461 [m/s^2].
- Z acc:      9.81 [m/s^2].
- P-DOT:      0 [rad/s^2].
- Q-DOT:      0 [rad/s^2].
- R-DOT:      0 [rad/s^2].

- Alpha:       10.2084 [deg].
- Sideslip:    20 [deg].
- Roll rate:   0 [-] (p*BREF/(2VREF)).
- Pitch rate:  0 [-] (q*CREF/(2VREF)).
- Yaw rate:    0 [-] (r*BREF/(2VREF)).
- Control flap1r: 0 [deg].
- Control flap2r: 0 [deg].
- Control aileronr: 18.9543 [deg].
- Control elevr:  4.89144 [deg].
- Control rudder1: 19.3475 [deg].
done.
- Updating vlm model in Aero.lattice_defo...done.
- Solution summary exported to C:\NeoCASS_PG\Examples\PROVA\static_3second\static2_man_1.txt file.

completed.
```



# Running another ‘TRIM’ and ‘Rigid VLM/DLM’ analysis

